

Towards Multiscale Simulations of Cloud Turbulence

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(Prof. Christos Vassilicos)

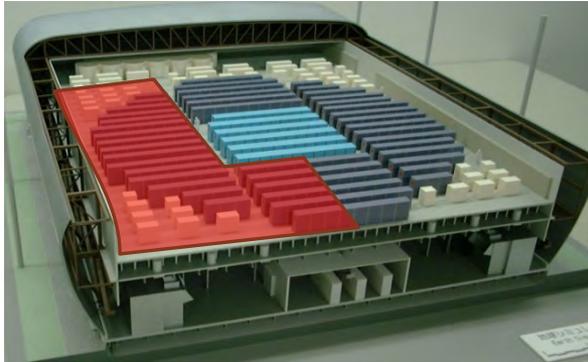
International MetStorm Conference
9 June, 2011

*****Some figures and slides are removed from original talk*****

Contents of my talk

- ❑ MSSSG (Multi-Scale Simulator for the Geoenvironment)
- ❑ High-resolution cloud simulations (LES) with MSSSG-Bin microphysical scheme
 - ❑ Turbulent collisions of droplets
 - ❑ RICO
- ❑ DNS for colliding droplets in high-Re flows
 - ❑ Our numerical schemes
 - ❑ validation of turbulent collision models

Earth Simulator 2



Earth Simulator

Mar. 2002 – Sept. 2008

Processors : 5,120 (640 nodes)

Peak performance : 40 TFLOPS

Main memory : 10 TB



Earth Simulator 2

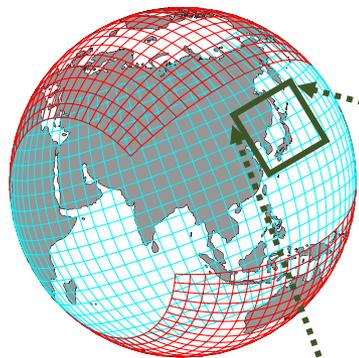
Mar. 2009 -

Processors : 1,280 (160 nodes)

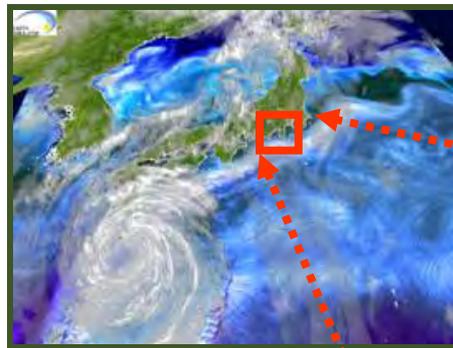
Peak performance : 131 TFLOPS

Main memory : 20 TB

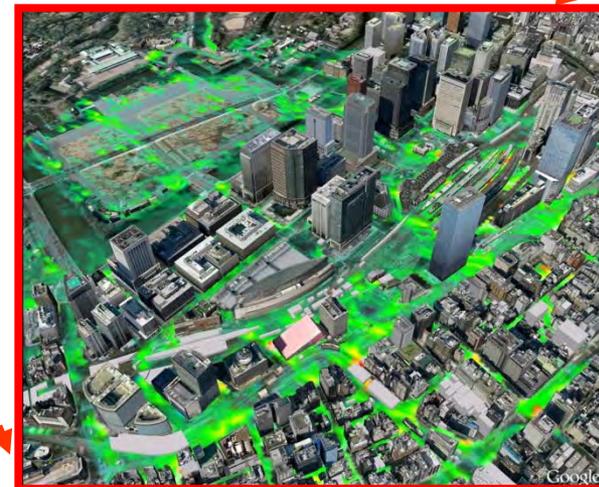
Multi-Scale Simulator for the Geoenvironment (MSSG)



global scale



mesoscale



urban scale

- Applicable to global, regional and local scales seamlessly
- Ying-Yang grid for globe
- Consists of 3 modes; atmos. / ocean / coupled
- Highly optimized for the Earth Simulator (ES)

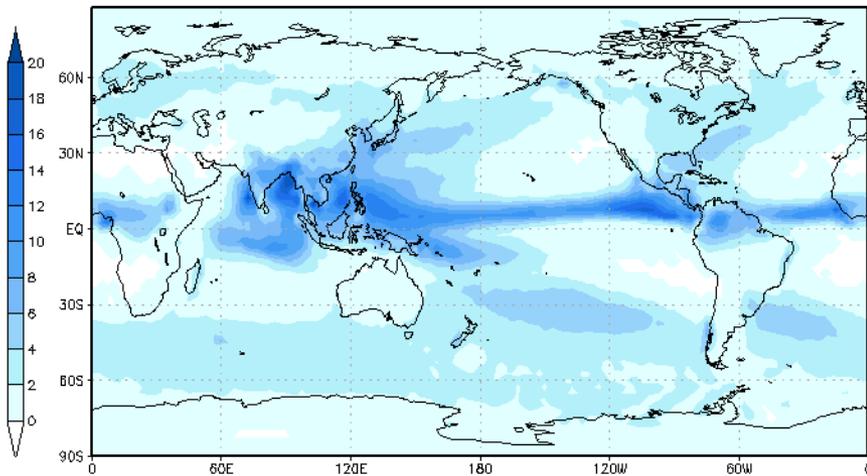


Data SIO, NOAA, U.S. Navy, NGA, GEBCO
Data © 2009 MIRC/JMA
Image © 2006 TerraMetrics

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Seasonal simulation

Observation
(CMAP, 1979-2001JJA)



MSSG-A
($\Delta_H=40$ km, 32 levels, 5yrs ave-JJA)

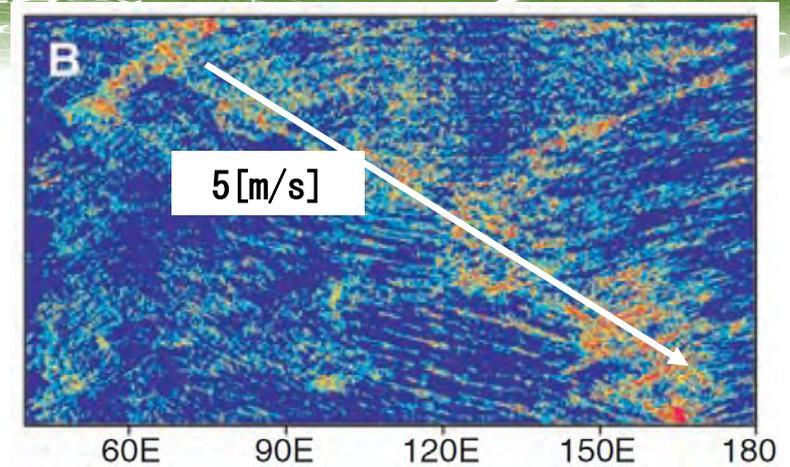
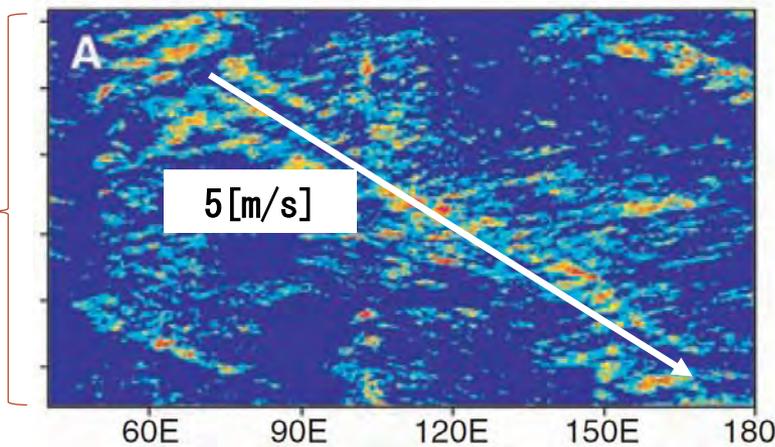


precipitation at JJA

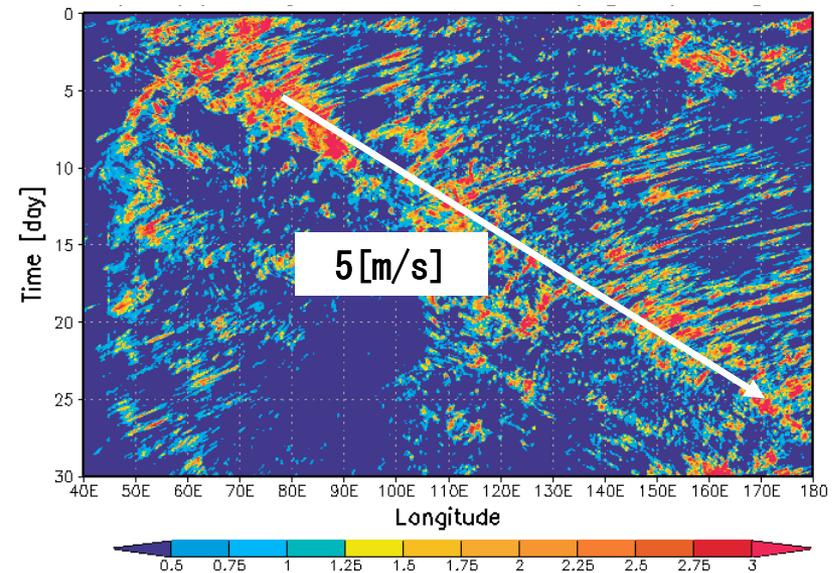
MJO experiment

NICAM-7km (Miura et al., 2008)

observation (TRMM 3B42)

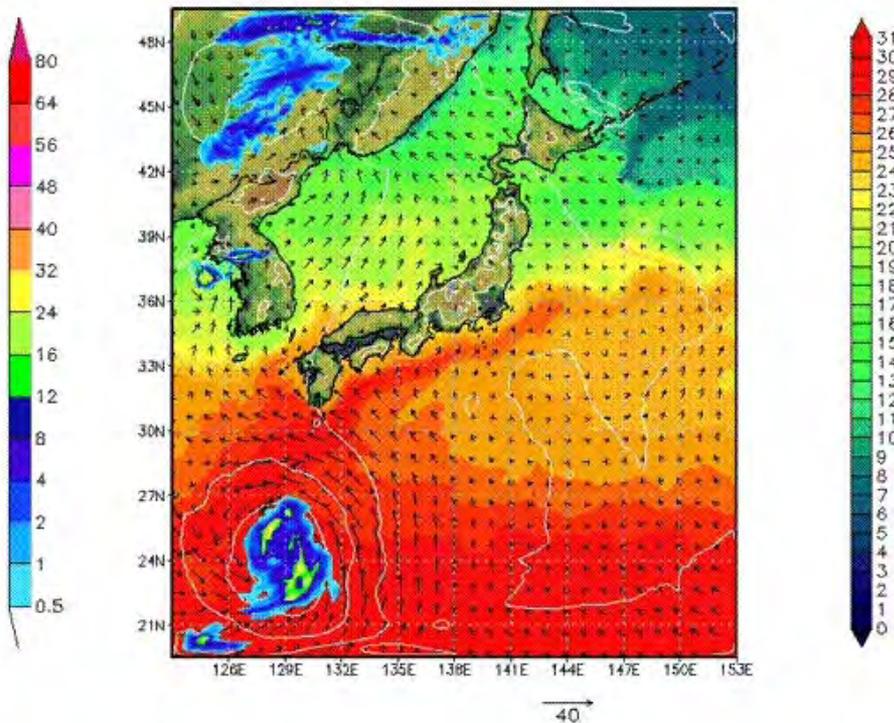
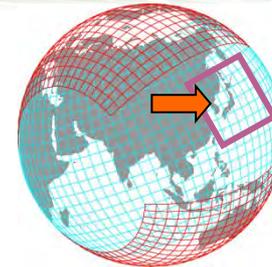


MSSG-10km



30 days from Dec 15, 2006

Coupled simulation for a Typhoon



$\Delta_H=2.7$ km, 72 layers



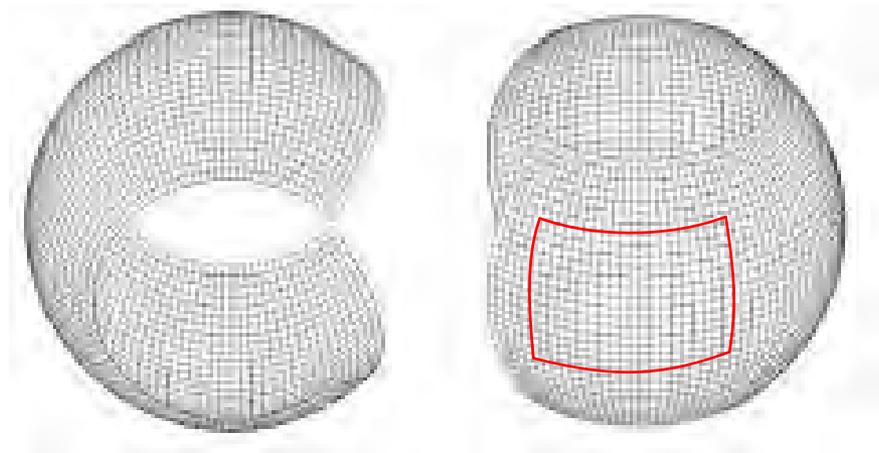
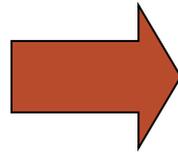
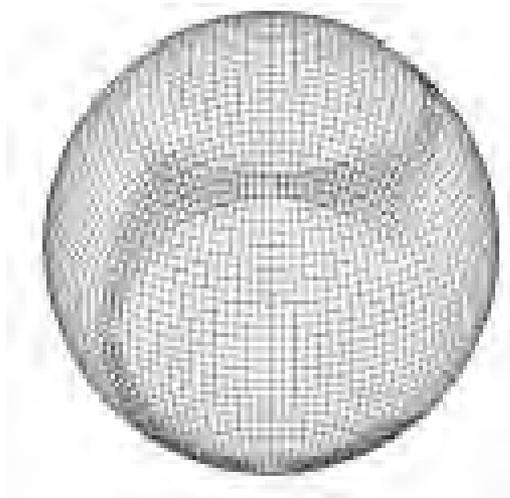
MSSG result is
operationally
provided to



High-resolution cloud simulations with Bin scheme

turbulence (large-eddy)
resolving mesoscale simulation

Use of MSSSG as a mesoscale model



**Yin-Yang system
for global simulations**

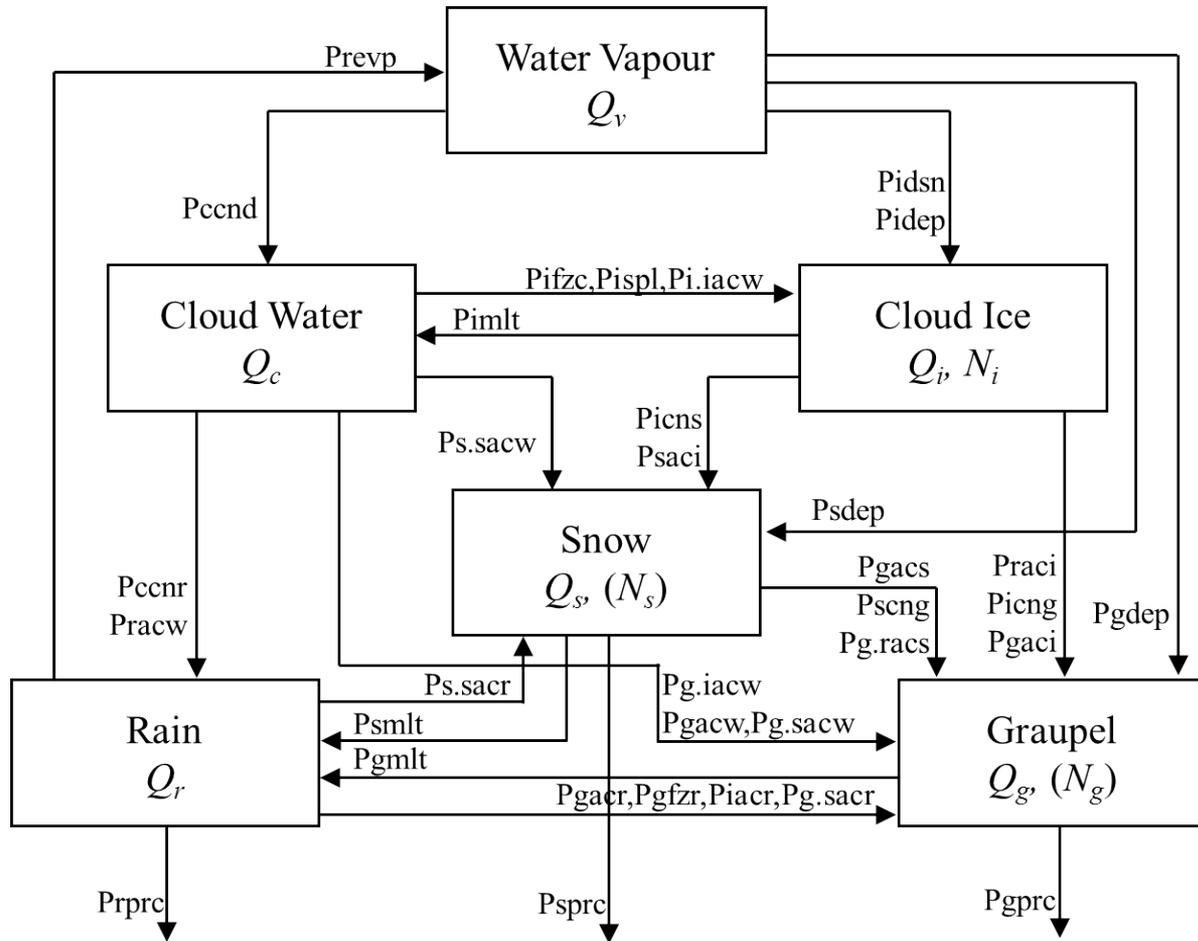
**lat-long system
for regional simulations**

Ref.

Kageyama & Sato (2004) *GGG*

Baba et al. (2010) *MWR*

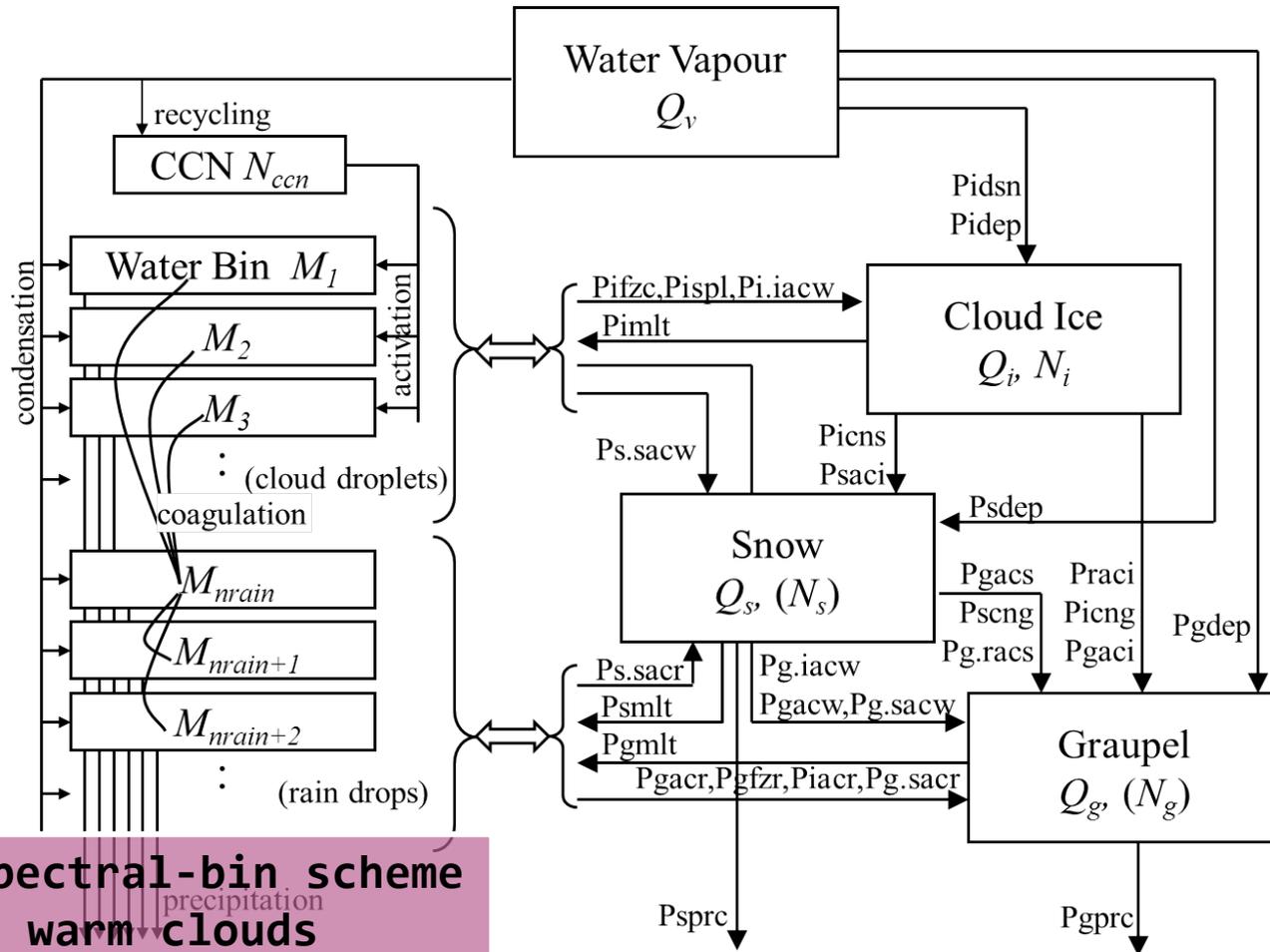
Bulk microphysical scheme



MSSG-Bulk model

(Reisner et al. (1998) with modification by Thompson (2004))

Bulk-Bin hybrid microphysical scheme



purely spectral-bin scheme
for warm clouds

MSSG-Bin model
(Onishi & Takahashi, submitted)

Collision growth calculation in Bin scheme

Stochastic Collision Equation (SCE)

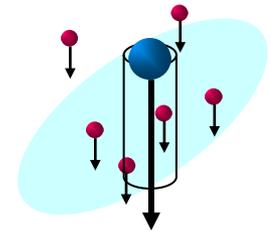
$$\left(\frac{\partial n_p(r)}{\partial t} \right)_{col} = \frac{1}{2} \int_0^r K_c(r'', r') n_p(r'') n_p(r') dr' - \int_0^\infty K_c(r, r') n_p(r) n_p(r') dr'$$

Collision kernel

Gravitational (Hydrodynamic) Collision Kernel (No turbulent collisions)

$$K_c(r_1, r_2) = \pi R^2 |V_\infty(r_1) - V_\infty(r_2)|$$

(R : collision radius ($=r_1+r_2$), V_∞ :settling velocity)

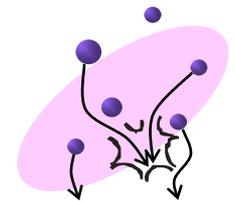


Turbulent Collision Kernel

$$\langle K_c(r_1, r_2, l_\eta, \text{Re}_\lambda) \rangle = 2\pi R^2 \langle |w_r| \rangle g(R)$$

$|w_r|$: radial relative velocity at contact (Wang et al. 2000)

$g(R)$: radial distribution function at contact (Onishi 2005, Onishi et al. 2007 etc...)



Algorithm for explicit turbulent collision calculation

MSSG

Dynamics

- compressive N-S eq. (static Smagorinsky model)
- etc...

Flow turbulent statistics

$$\begin{aligned}\varepsilon &\approx \varepsilon_{SGS} \\ &= (C_s \bar{\Delta})^2 |\bar{S}|^3 \\ u' &\approx \bar{\Delta} |S| / 2\end{aligned}$$

local isotropy

$$\begin{cases} l_\eta = (\nu^3 / \varepsilon)^{1/4} \\ l_\lambda = \sqrt{\frac{15\nu}{\varepsilon}} u' \\ \text{Re}_\lambda = \frac{u' l_\lambda}{\nu} \end{cases}$$

Microphysics (Bin method)

- collision growth
- condensation growth
- etc...

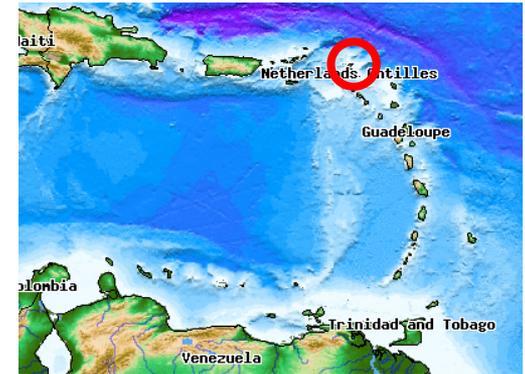
$$\langle K_c(r_1, r_2, l_\eta, \text{Re}_\lambda) \rangle$$

RICO (Rain In Cumulus over the Ocean)

Field campaign for shallow cumulus developing over the ocean near the Barbuda islands (18.0N;61.5W).

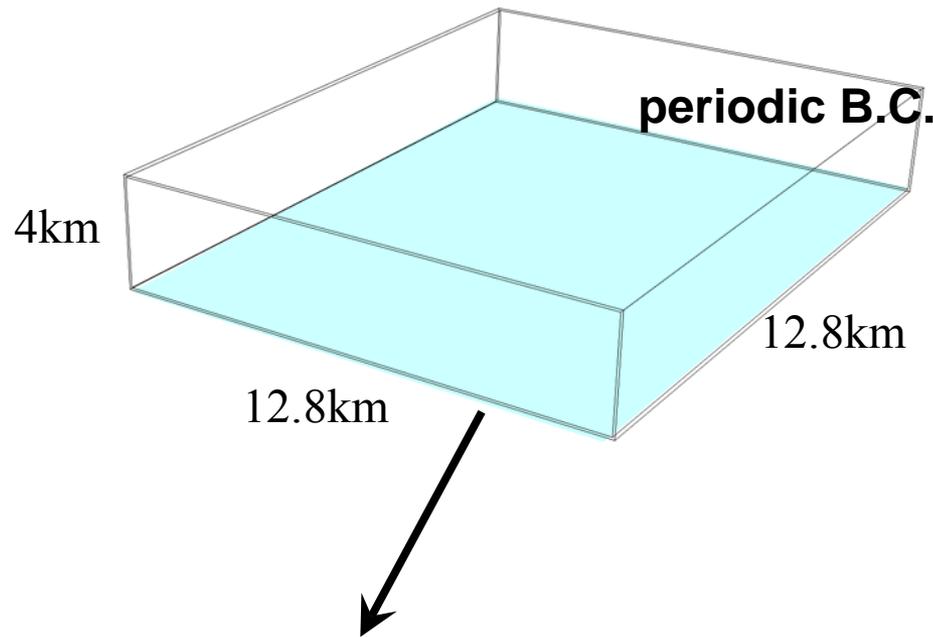


www.eol.ucar.edu/projects/rico/



RICO model intercomparison

24h simulation with $\Delta x = \Delta y = 100\text{m}$, $\Delta z = 40\text{m}$



surface fluxes

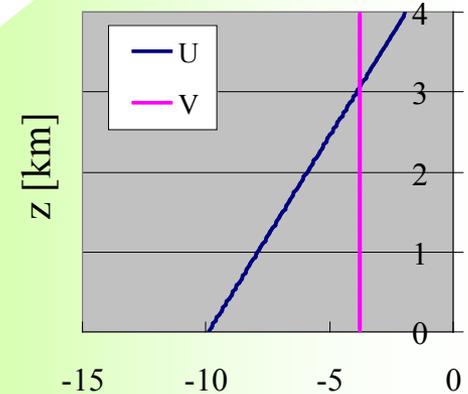
- Heat flux: $w \theta_1 = -C_h * |U| * (\theta_1 - SST * (p_0/p)^{R_d/c_p})$
- Water vapor flux: $w q_t = -C_q * |U| * (q_t - q_{sat}(T_{sfc}))$
- Momentum flux:

$$uw = -u * C_m * |U|$$

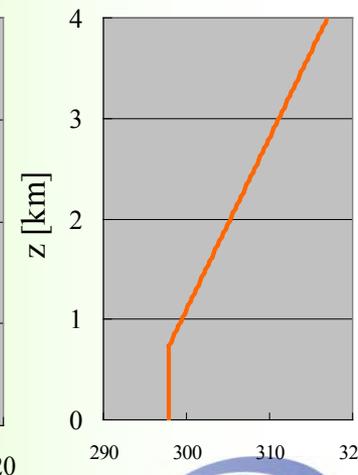
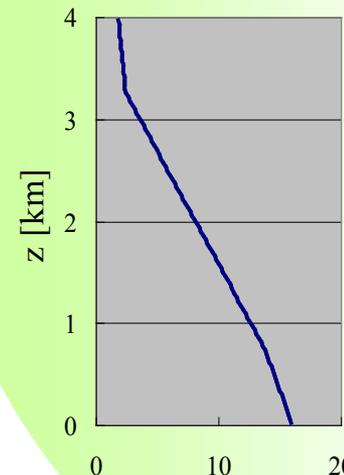
$$vw = -v * C_m * |U|$$

where, $C_m = 0.001229$, $C_h = 0.001094$, $C_q = 0.001133$

init. vert. prof.

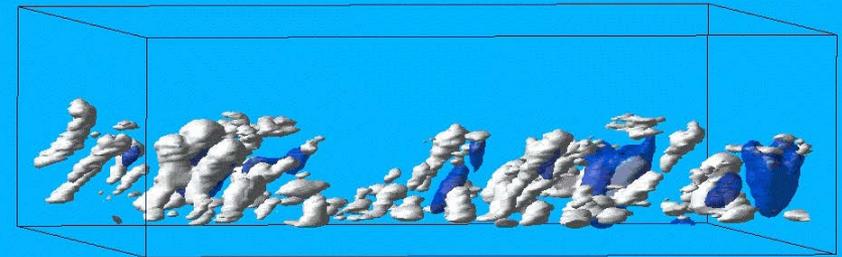
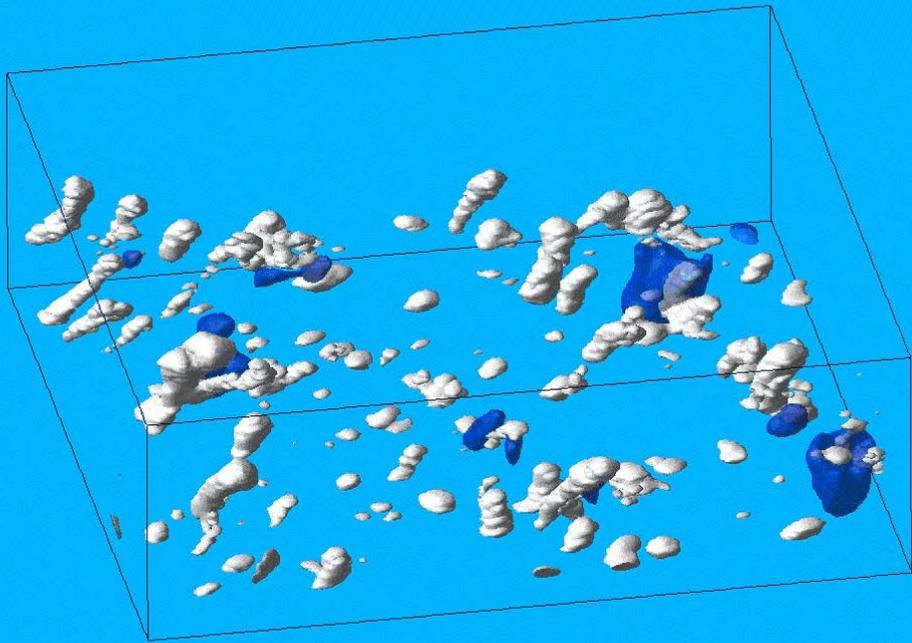


U, V [m/s]



extra 1-hour simulation for visualization (MSSG-Bulk)

$\Delta x = 100\text{m}$

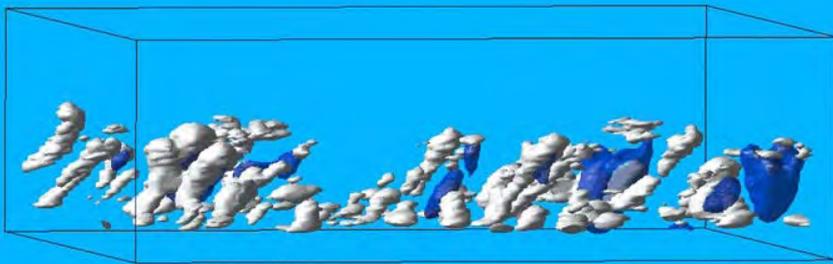


1-hour-simulation with MSSG-Bulk method (for visualization)

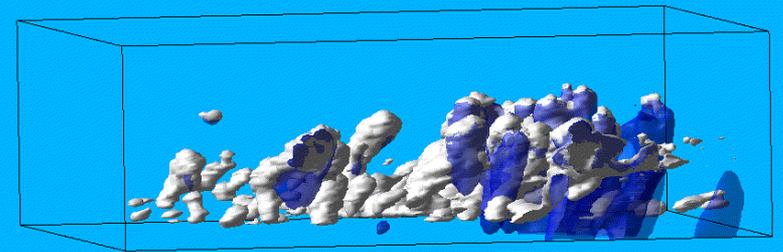
Visualization – Bulk v.s. Bin scheme

$\Delta x = 100\text{m}$

Bulk scheme



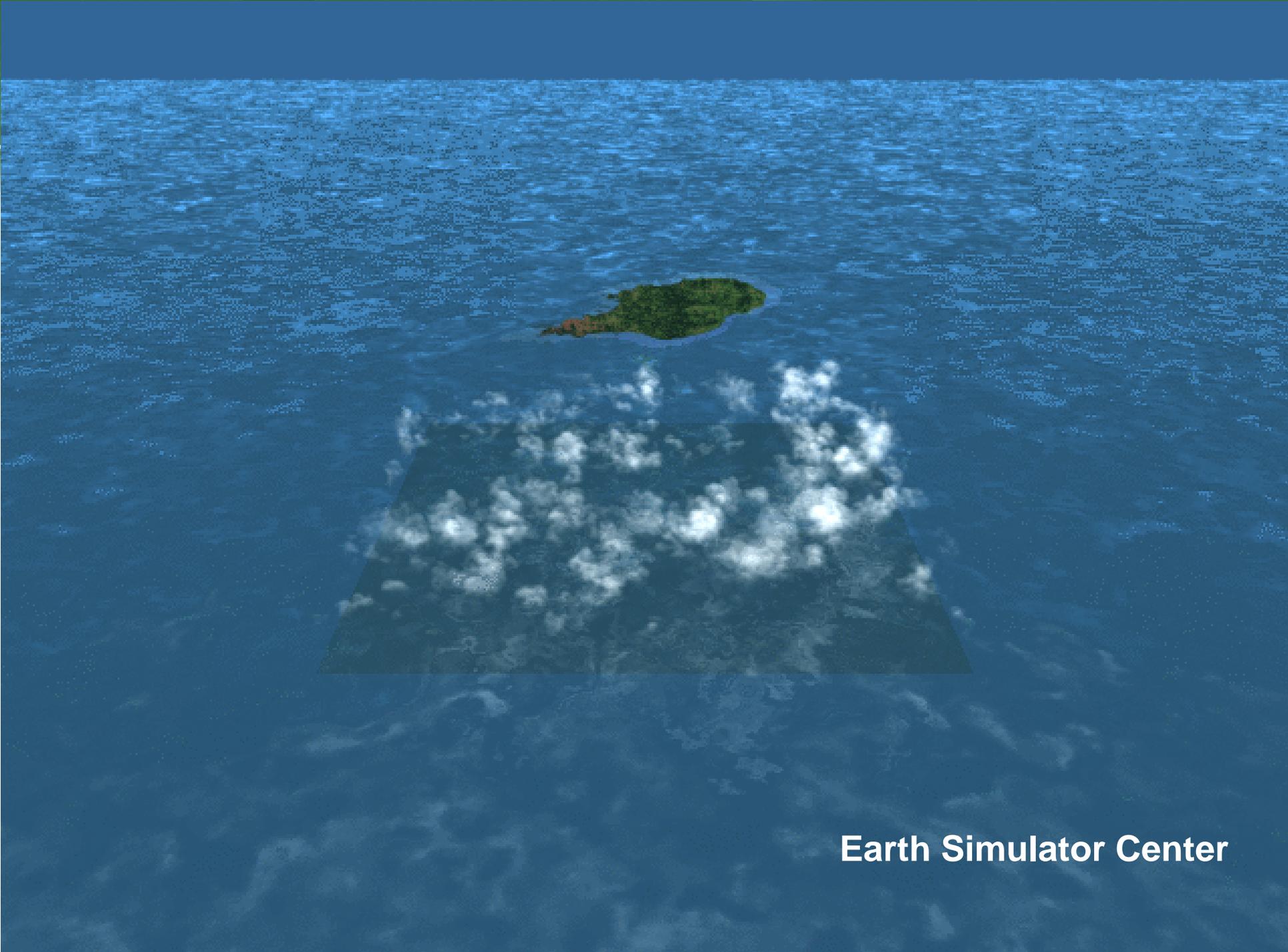
Bin scheme



($r > 40\mu\text{m}$ droplets are recognized as rain drops)

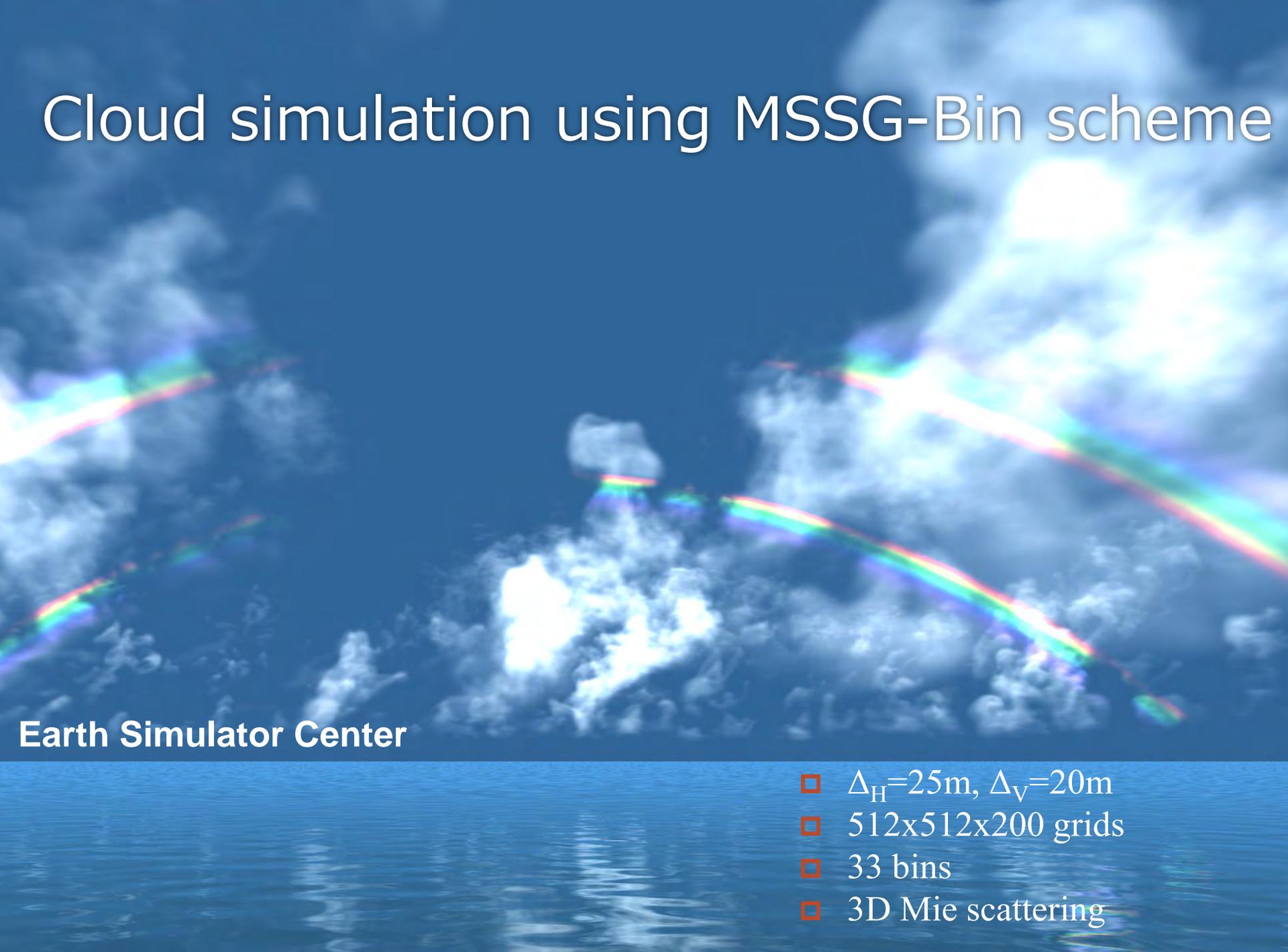
Clouds distribute uniformly in Bulk simulation (w/o CCN), while rather patchily in Bin simulation (with CCN).





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Cloud simulation using MSSG-Bin scheme



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- $\Delta_H=25\text{m}$, $\Delta_V=20\text{m}$
- 512x512x200 grids
- 33 bins
- 3D Mie scattering

with Kaiser-Wilhelm Memorial Church



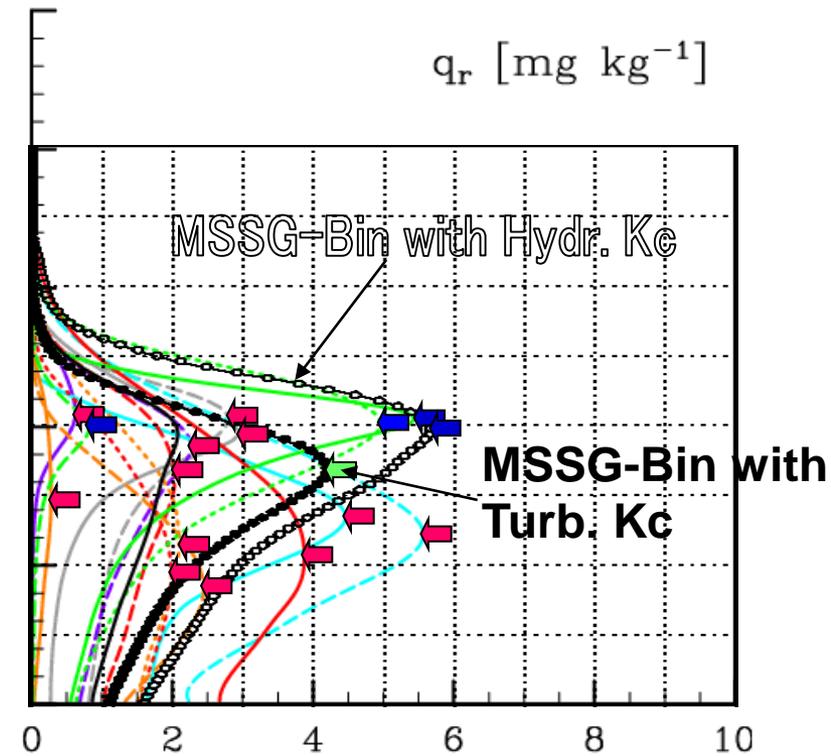
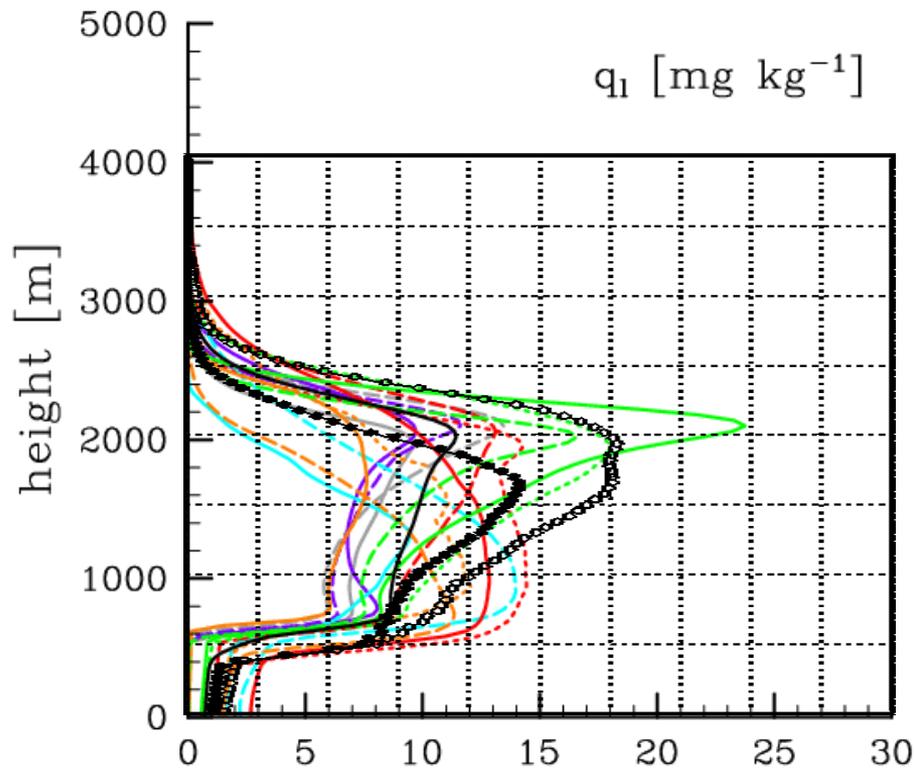
Image © 2010 AeroWest
© 2010 Tele Atlas
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高度 15メートル

Mixing ratios of liquid water (q_l) and rain water (q_r)



Significant impact of turbulent collisions

Can we really trust this result?

- Applicability of the turbulent collision model has not been confirmed.
 - $Re_\lambda = 10^{3\sim 4}$ in cumulus clouds,
 - while available DNS data is for $Re_\lambda < 10^2$.
- We need DNS data for high Re_λ .

DNS for colliding droplets in high-Re flows

- >Our numerical schemes
- >Validation of turbulent collision models

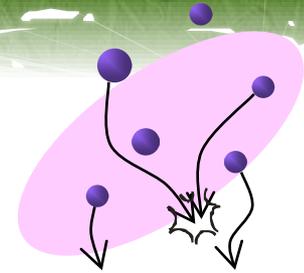
Turbulent collision kernel model in isotropic turbulence

$$\left\langle K_c \left(\underbrace{\frac{r_1}{l_\eta}, \frac{r_2}{l_\eta}}_{St}, \text{Re}_\lambda, \left(\frac{\rho_p}{\rho_f} \right) \right) \right\rangle = 2 \pi R^2 \langle |w_r| \rangle g(R)$$

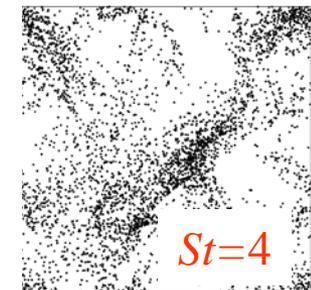
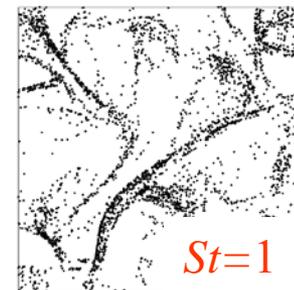
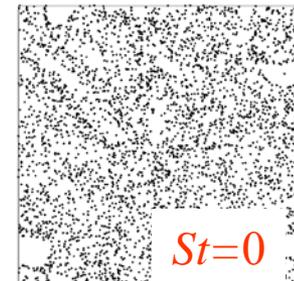
- R : collision radius ($=r_1+r_2$)
- $|w_r|$: radial relative velocity at contact
- $g(R)$: radial distribution function at contact



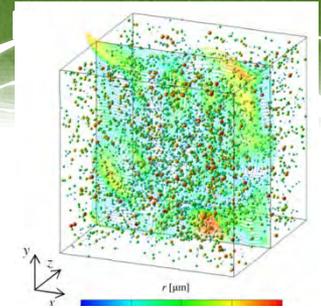
preferential distribution



$$St = \frac{\tau_p}{\tau_\eta} = \frac{2 \rho_p}{9 \rho_f} \left(\frac{r}{l_\eta} \right)^2$$



Recent DNS data on colliding inertial-particles in air turbulence



Flow: Euler
Particle: Lagrange

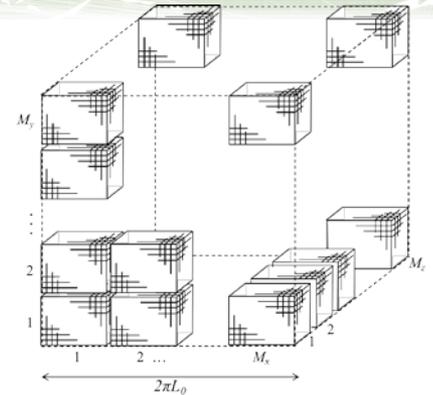
Paper name	fluid calculation	cell-index method	parallelization	$Re_{\lambda, \max}$
Wang et al.(2000) <i>JFM</i>	PSM	w	-	75.4
Reade&Collins(2000) <i>PF</i>	PSM	-	-	82.5
Zhou et al.(2001) <i>JFM</i>	PSM	w	-	58
Ayala et al.(2007) <i>JCP</i>	PSM	w	shared	72.4
Ayala et al.(2008) <i>NJP</i>	PSM	w	shared	72.4
Wang et al.(2008) <i>NJP</i>	PSM	w	shared	72.4
Woittiez et al.(2009) <i>JAS</i>	FDM	-	-	84.9
Onishi et al.(2009) <i>PF</i>	PSM	w/o	shared	68.4

Table 1 Review of recent studies on collision frequencies of inertia particles in stationary isotropic turbulence.

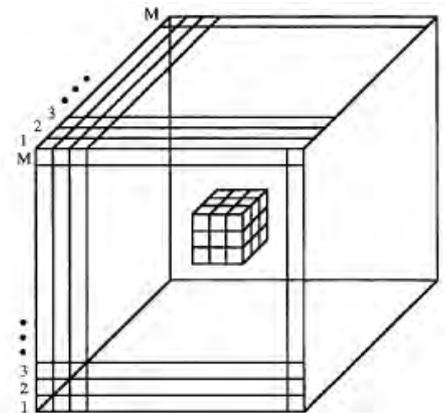
Pseudo-Spectral Model (PSM) has been used for flow!

Our numerical schemes for high-Re DNS

- Steady isotropic air turbulence:
 - **Finite-Difference Model (FDM)**
 - 4th-order conservative scheme (Morinishi et al. (1998)*JCP*)
 - MPI, i.e., distributed-memory parallelization, for **3D domain decomposition**
 - **RCF** (Reduced-Communication Forcing) to attain a stationary state (Onishi et al. (2011)*JCP*)
- Particle motion:
 - Lagrangian tracking method
 - **Cell-index method** for efficient collision detection
 - MPI for **3D domain decomposition**



3D domain decomposition

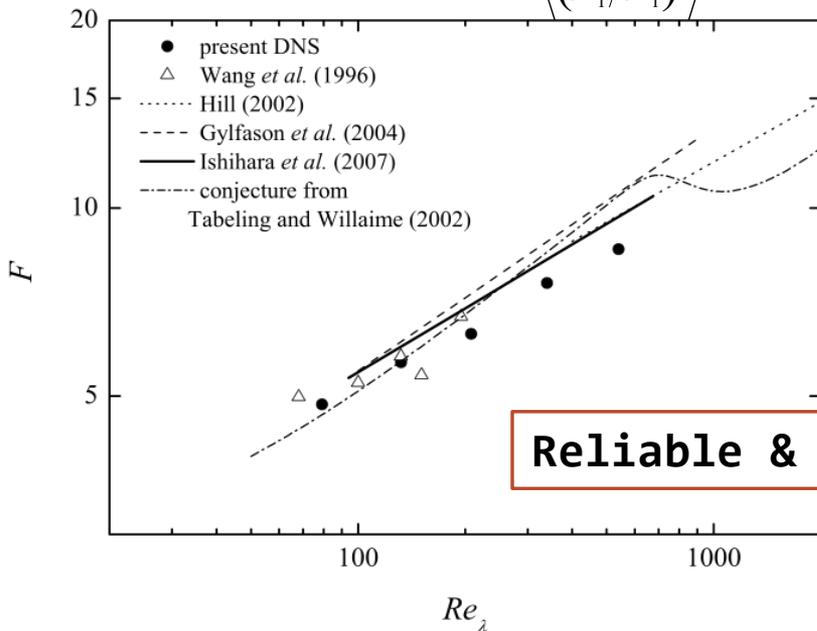


Cell-index method
(Allen & Tildesley (1987))

Checks of our code

Flow simulation

$$\text{Flatness factor: } F = \frac{\langle (\partial u_1 / \partial x_1)^4 \rangle}{\langle (\partial u_1 / \partial x_1)^2 \rangle^2}$$

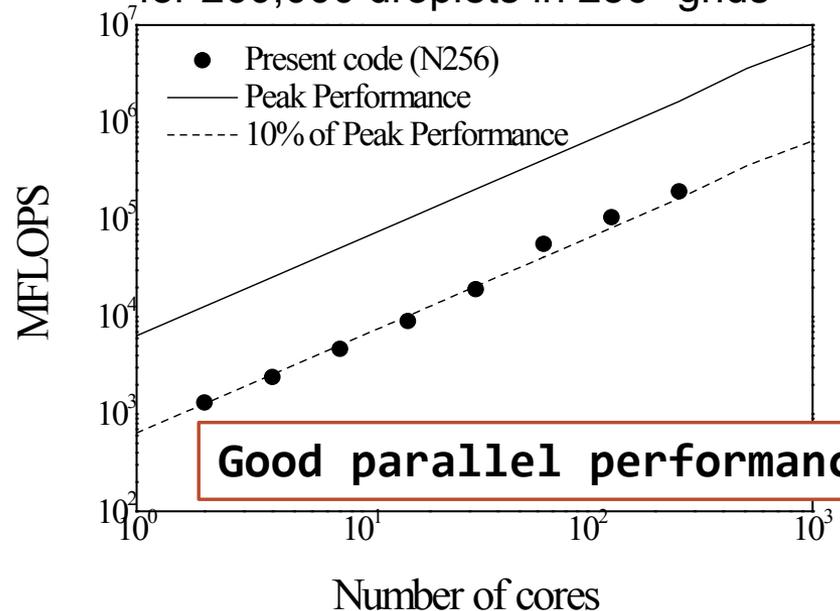


Reliable & Fast

Present FDM is estimated to be **x3.8 faster** than conventional PSM (not shown here).

Flow & Particle simulation

Performance on ALTIX
for 260,000 droplets in 256^3 grids



Good parallel performance

REF: Onishi *et al.* (2011) *JCP*

Collision kernels of $St=1$ droplets

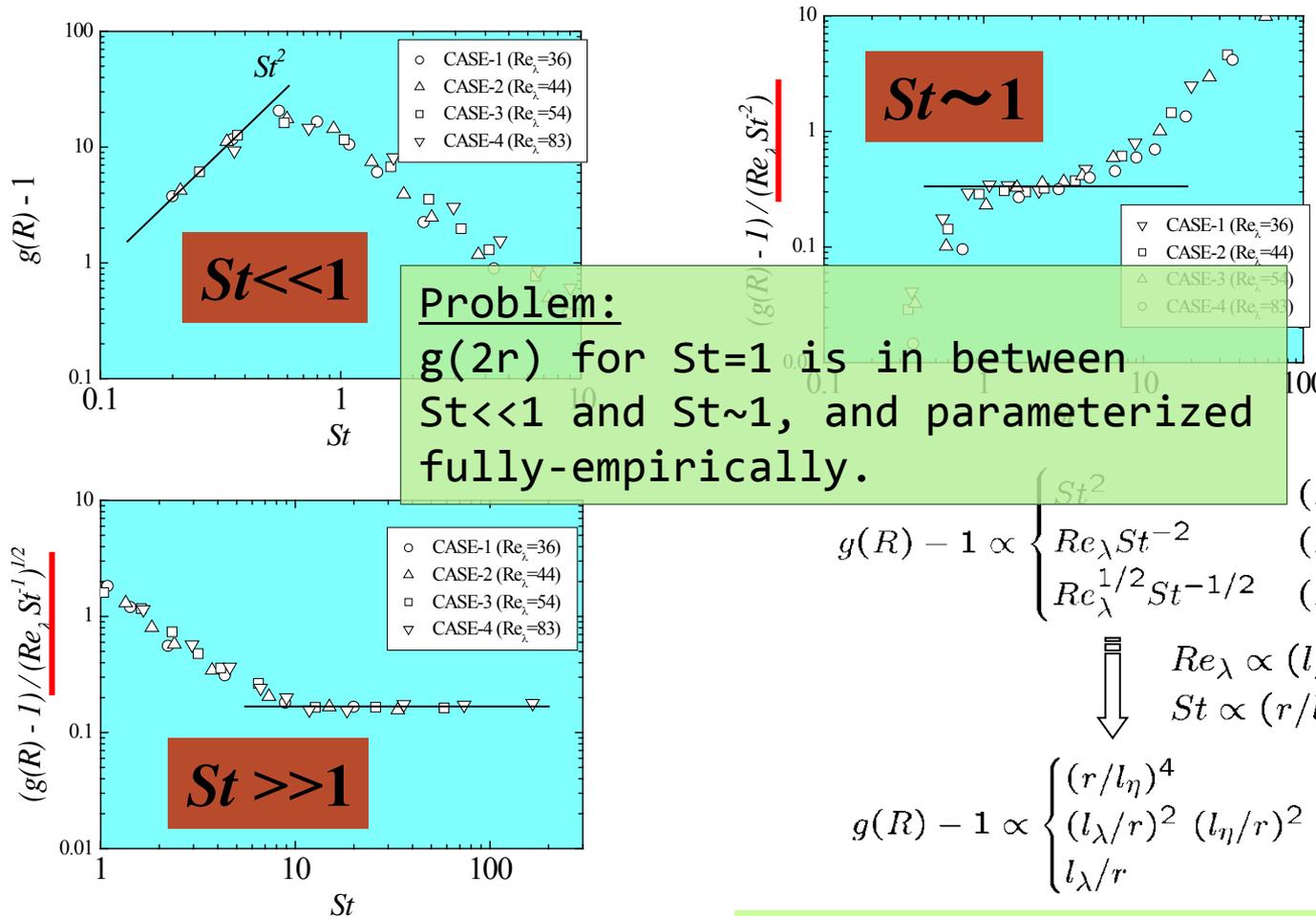
$Re_\lambda=340$
1000³ grids,
50million particles

**newly obtained data appears
in the contribution paper**

Collision data for
 $Re_\lambda \sim 540$ (2000³ grids,
billion particles) is
obtainable on ES2

Radial distribution function - $g(R=2r)$ -model

$$\langle K_c(r,r) \rangle = 2\pi R^2 \langle |w_r| \rangle \underline{g(2r)}$$



$$g(R) - 1 \propto \begin{cases} St^2 & (St \ll 1) \\ Re_\lambda St^{-2} & (St \sim 1) \\ Re_\lambda^{1/2} St^{-1/2} & (St \gg 1) \end{cases}$$

$$\begin{aligned} \Downarrow \\ Re_\lambda &\propto (l_\lambda/l_\eta)^2 \\ St &\propto (r/l_\eta)^2 \end{aligned}$$

$$g(R) - 1 \propto \begin{cases} (r/l_\eta)^4 & (St \ll 1) \\ (l_\lambda/r)^2 (l_\eta/r)^2 & (St \sim 1) \\ l_\lambda/r & (St \gg 1) \end{cases}$$

Empirical, but with some physical support

Concluding Remarks

- **MSSG** (Multi-Scale Simulator for the Geoenvironment)
 - Non-hydrostatic atmos-ocean coupled model
 - Yin-Yang grid

- High-resolution cloud simulations (LES) with MSSG-Bin scheme
 - useful to see the turbulence role in clouds
 - $\Delta=25\text{m}$ simulations are feasible on the ES2

- DNS for colliding droplets in high-Re flows
 - useful to check the applicability of turbulent collision models to cloud turbulence with $\text{Re}_\lambda=10^{3\sim 4}$
 - Data for up to $\text{Re}_\lambda=340$ has been obtained, and one for $\text{Re}_\lambda=540$ is coming.
 - These atmos. flows have energy scales L of $O(1\text{m})$.

Turbulence models validated by the DNS for $L=O(10\text{m})$ will strengthen the $\Delta=O(10\text{m})$ cloud simulations, on $O(10 \text{ PFLOPS})$ supercomputers!

