

Large Eddy Simulation with Adaptive Moving Meshes

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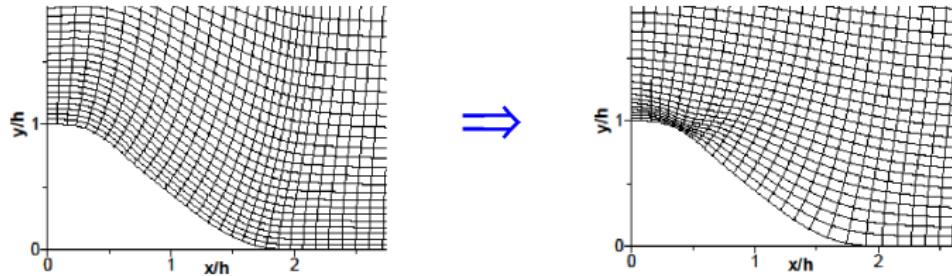
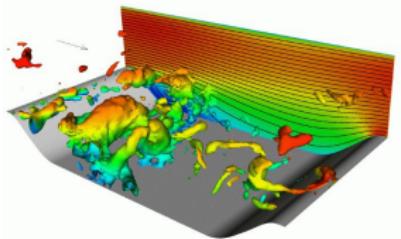
Outline

- ① Introduction
- ② Moving Mesh Method
- ③ Physically Motivated Qols
- ④ Current Research

Scientific Goals



- Optimizing LES via r-adaption ("redistribution")
- Appropriate monitor functions for LES
- Multi-scale modelling with variable filter width
- Adaptive scale separation



- physical domain Ω with coordinates $\mathbf{x} = (x_1, \dots, x_n)^T$
- computational domain Ω_c with coordinates $\xi = (\xi_1, \dots, \xi_n)^T$
- solution of the physical PDE $\mathbf{u} = \mathbf{u}(\mathbf{x}, t)$
- 1-1 coordinate transformation $\mathbf{x} = \mathbf{x}(\xi, t)$
- minimise mesh adaptation functional

$$\mathcal{I}[\xi] = \frac{1}{2} \int_{\Omega} \sqrt{g} \left(\sum_i \nabla \xi_i^T G^{-1} \nabla \xi_i \right) d\mathbf{x}$$

Setup

- physical domain Ω with coordinates $\mathbf{x} = (x_1, \dots, x_n)^T$
- computational domain Ω_c with coordinates $\xi = (\xi_1, \dots, \xi_n)^T$
- solution of the physical PDE $\mathbf{u} = \mathbf{u}(\mathbf{x}, t)$
- 1-1 coordinate transformation $\mathbf{x} = \mathbf{x}(\xi, t)$
- minimise mesh adaptation functional

$$\mathcal{I}[\xi] = \theta \int_{\Omega} \sqrt{g} \left(\sum_i \nabla \xi_i^T G^{-1} \nabla \xi_i \right)^{\frac{nq}{2}} dx + (1 - 2\theta) n^{\frac{nq}{2}} \int_{\Omega} \frac{\sqrt{g}}{(\|J\| \sqrt{g})^q} dx$$

The Mesh Moving PDE (MMPDE)

Interchanging the roles of dependent and independent variables in the (modified) gradient flow equation of $\mathcal{I}[\xi]$ leads to the MMPDE:

$$\tau \frac{\partial \mathbf{x}}{\partial t} = P \left[\sum_{i,j} a_{ij} \frac{\partial^2 \mathbf{x}}{\partial \xi_i \partial \xi_j} - \sum_i b_i \frac{\partial \mathbf{x}}{\partial \xi_i} \right],$$

where

$$a_{ij} = (\nabla \xi_i) \cdot G^{-1}(\nabla \xi_j), \quad b_i = \sum_j (\nabla \xi_i) \cdot \frac{\partial G^{-1}}{\partial \xi_j}(\nabla \xi_j).$$

$G(\Psi)$: Monitor function depending on some QoI Ψ

The Monitor Function $G(\Psi)$

Monitor functions for multiple QoS:

$$G(\Psi) = \omega(\Psi)I,$$

where

$$\omega(\Psi) = \sqrt{1 + \frac{\alpha}{\Psi_M} \sum_{k=1}^N \left(\frac{\Psi_k}{\Psi_{k,max}} \right)^2}$$

or

$$\omega(\Psi) = 1 + \frac{\alpha}{\sum_{k=1}^N w_k} \sum_{k=1}^N w_k \left[\frac{(1-\beta)\alpha_k + \beta\|\Psi_k\|}{(1-\beta)\alpha_k + \beta M_k} \right]$$

Moving Meshes in LESOCC2

Finite Volume Method

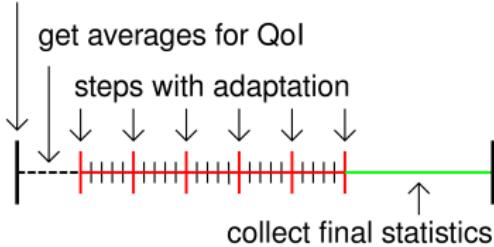
Filtered ALE formulation for mass and momentum conservation

Moving Meshes in LESOCC2

Finite Volume Method

Filtered ALE formulation for mass and momentum conservation

statistically converged flow on
stationary grid

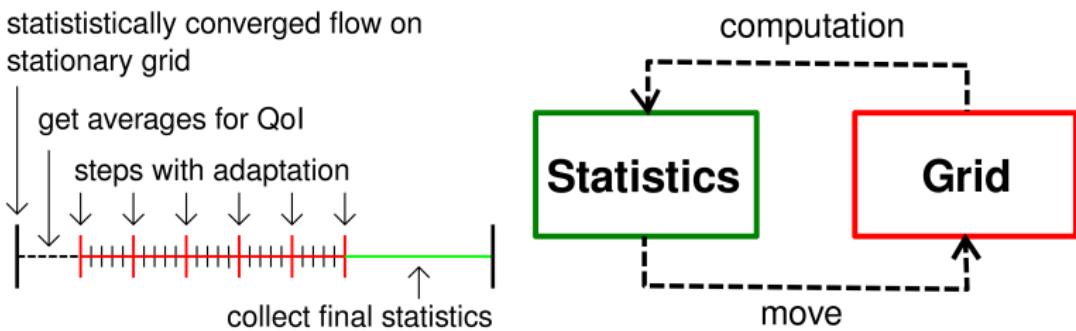


Moving Meshes in LESOCC2



Finite Volume Method

Filtered ALE formulation for mass and momentum conservation



Physically Motivated Qols

$\langle \cdot \rangle :=$ average in homogeneous direction and time

① Gradient of streamwise velocity: $\Psi = \nabla \langle u \rangle$

② Modelled TKE: $\Psi = \frac{\langle k_{sgs} \rangle}{\langle k_{res} \rangle + \langle k_{sgs} \rangle}$

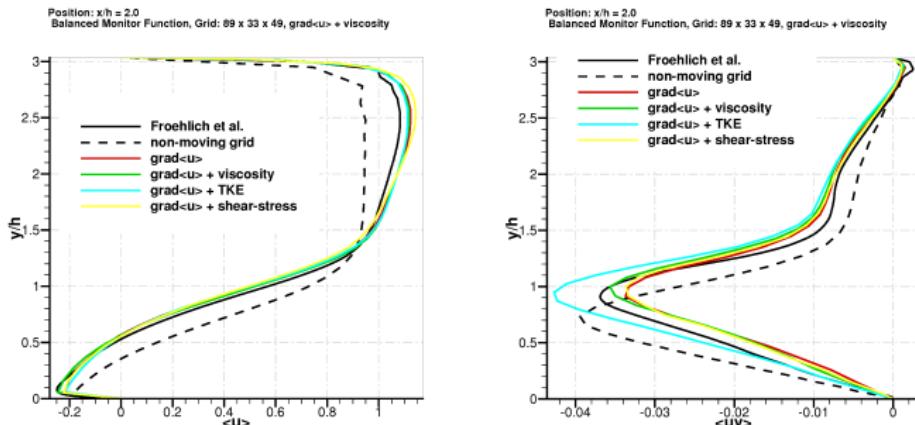
③ Turbulent viscosity: $\Psi = \langle \nu_t \rangle$

④ Turbulent shear: $\frac{\langle \tau_{12}^{mod} \rangle}{\langle \tau_{12}^{mod} \rangle + \langle u' v' \rangle}$

Results

Flow over periodic hills ($Re = 10595$)

- Grid 1: $196 \times 128 \times 186 \rightarrow \approx 4.6\text{mio points}$ (—)
- Grid 2: $89 \times 33 \times 49 \rightarrow \approx 144\text{k points}$ (- -)



Production of TKE as QoI

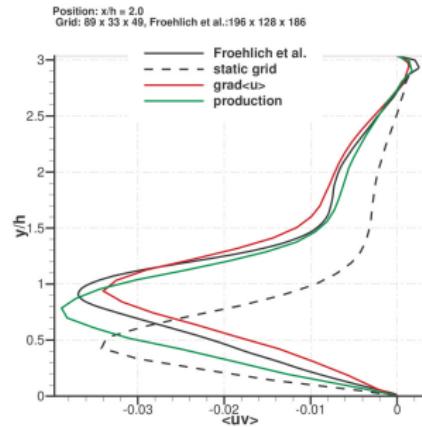
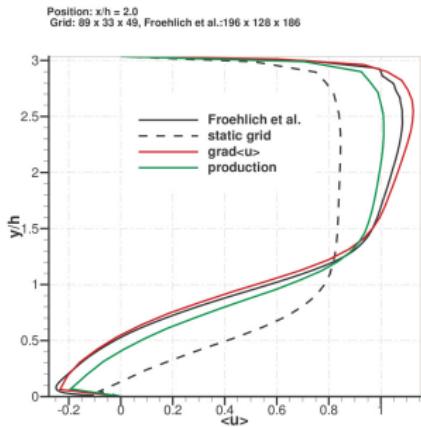
Idea: resolve production – model dissipation

Time-averaged production: $-\sum_{ij} \langle u'_i, u'_j \rangle \frac{\partial \langle u_i \rangle}{\partial x_j}$

Production of TKE as QoI

Idea: resolve production – model dissipation

Time-averaged production: $-\sum_{ij} < u'_i, u'_j > \frac{\partial < u_i >}{\partial x_j}$



Summary and Current Research

- High potential of mesh moving methods based on adaptive scale separation
- Resolve as much physics as possible with given DoFs
- Extension to coupled turbulence and wave propagation
 - ⇒ rotating annulus (Egbers/Harlander experiment)
- Develop efficient strategies for instationary scale separation
- Sensitivity-based dynamic mesh movement w.r.t. QoI